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Lecture CFD-3

CFD modelling of multiphase flows

Simon Lo
CD-adapco
Trident House, Basil Hill Road
Didcot, OX11 7HJ, UK
simon.lo@cd-adapco.com

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Multiphase models and applications

- VOF
 - Free surface flows
- LMP
 - Droplet flows
 - Liquid film
- DEM
 - Particle flows
- EMP
 - Particle flows
 - Bubbly flows
 - Population balance
 - Boiling heat and mass transfers
 - Interphase mass transfer

Volume of Fluid (VOF) model

- Solve equation for volume fraction (based on conservation of mass) to identify location of gas and liquid.

$$\frac{\partial \alpha_i}{\partial t} + \nabla \cdot (\alpha_i u) = \dot{m}_i$$

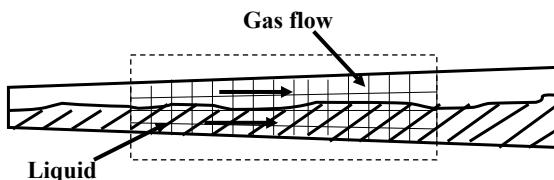
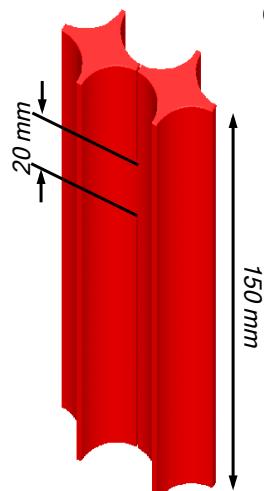
- Momentum equation for the gas-liquid mixture:

$$\frac{\partial}{\partial t} (\rho_m u_i) + \frac{\partial}{\partial x_j} (\rho_m u_j u_i - \tau_{ij}) = - \frac{\partial p}{\partial x_i} + \rho_m g_i + M$$

- Properties of mixture:

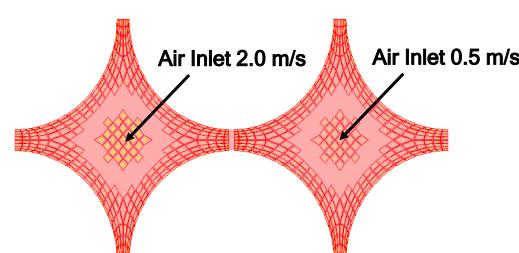
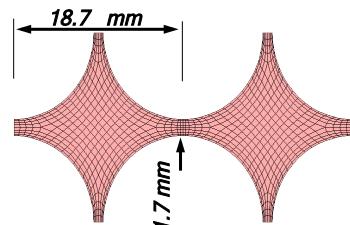
$$\rho_m = \sum_{i=1}^N (\alpha_i \rho_i)$$

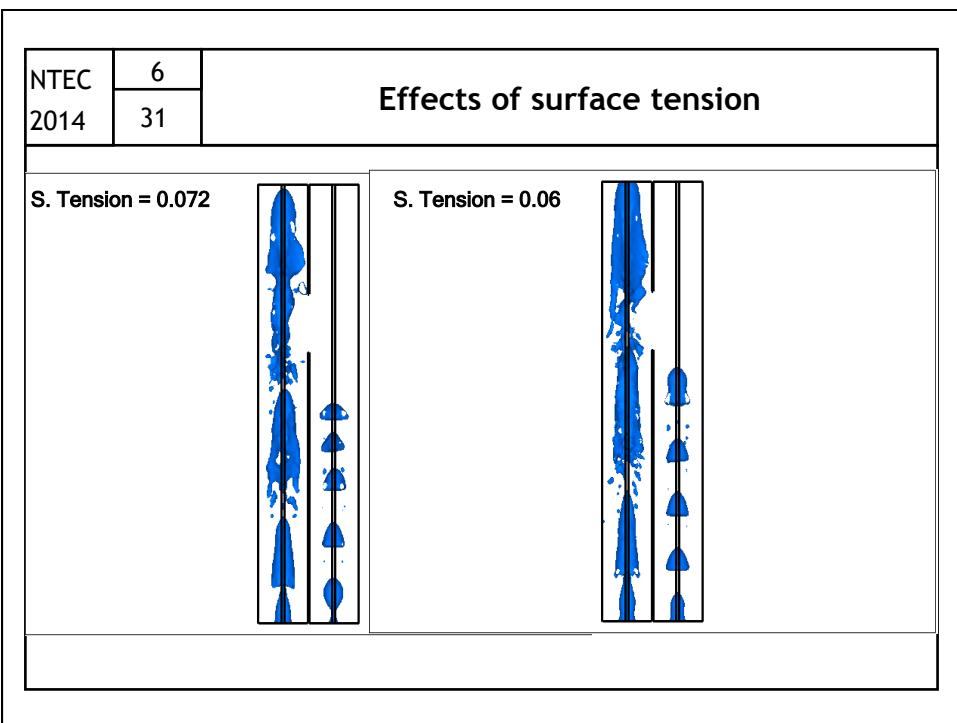
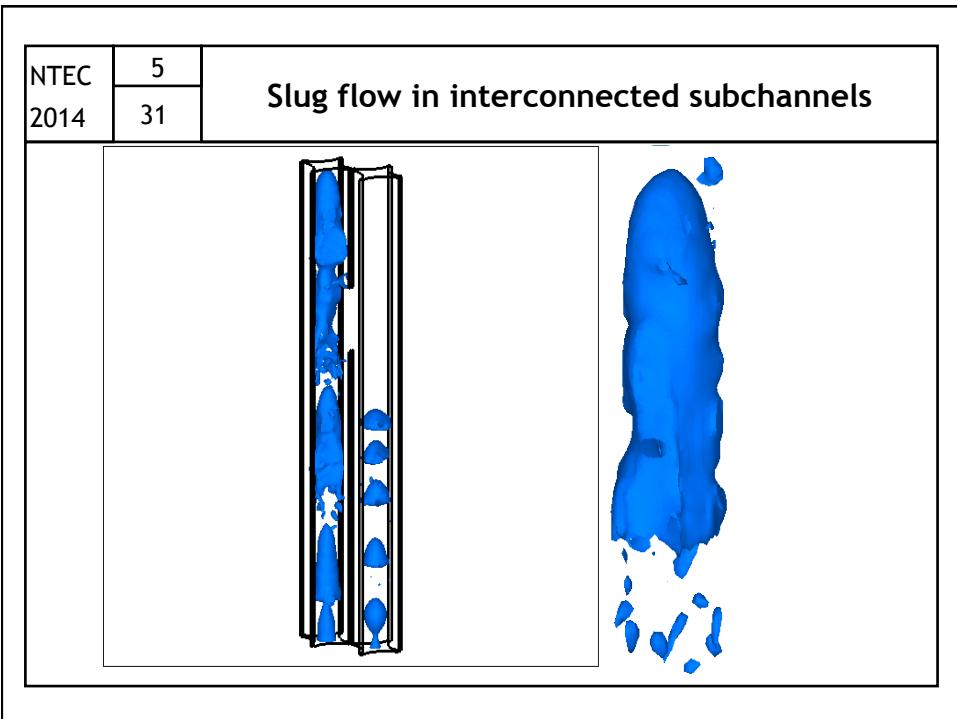
$$\mu_m = \sum_{i=1}^N (\alpha_i \mu_i)$$

**Slug flow in interconnected subchannels**

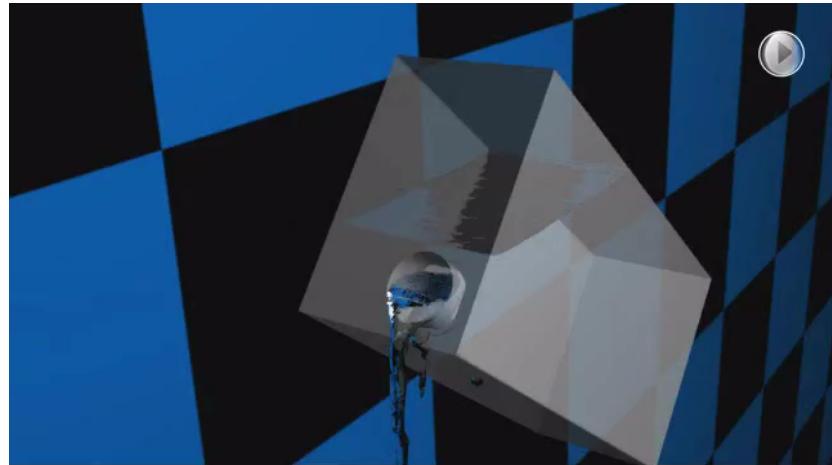
Calculation grid 204,512 cells

Water Inlet 0.23 m/s





Free surface flow in drink carton

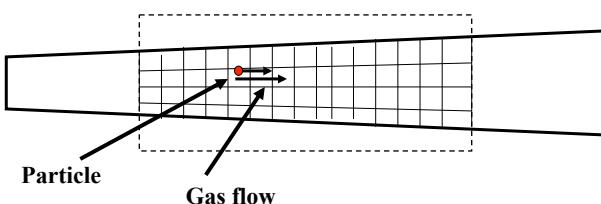


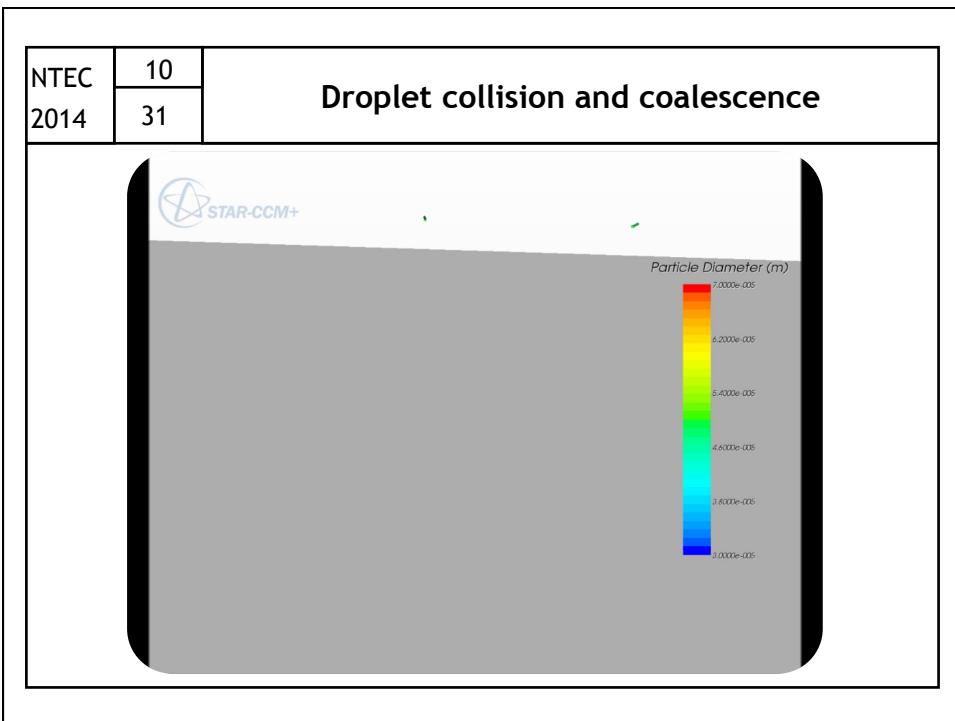
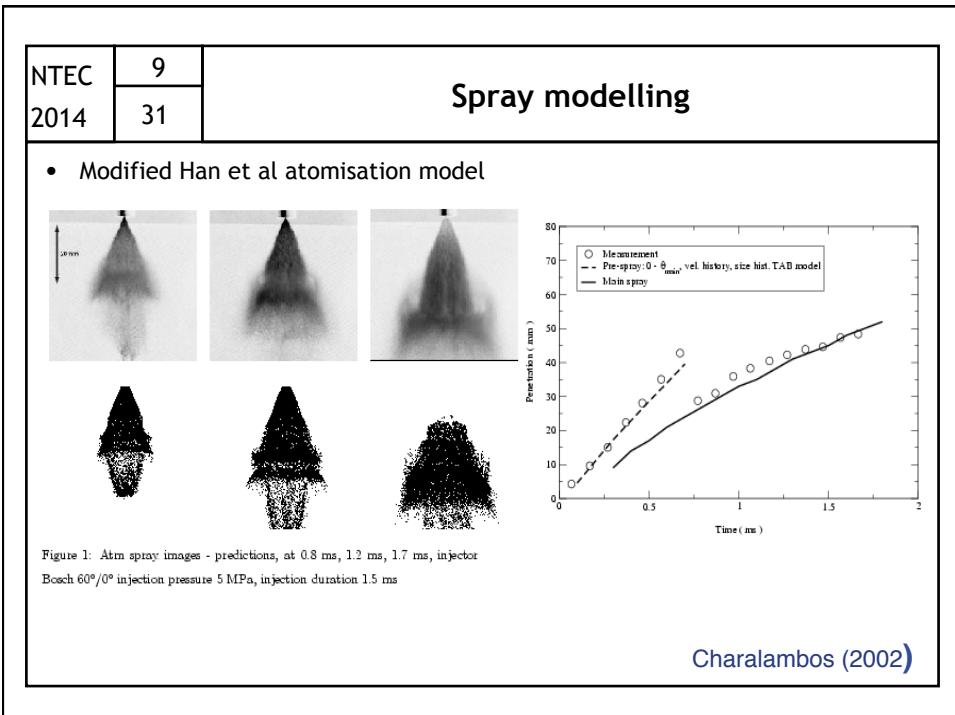
Lagrangian model for particle flows

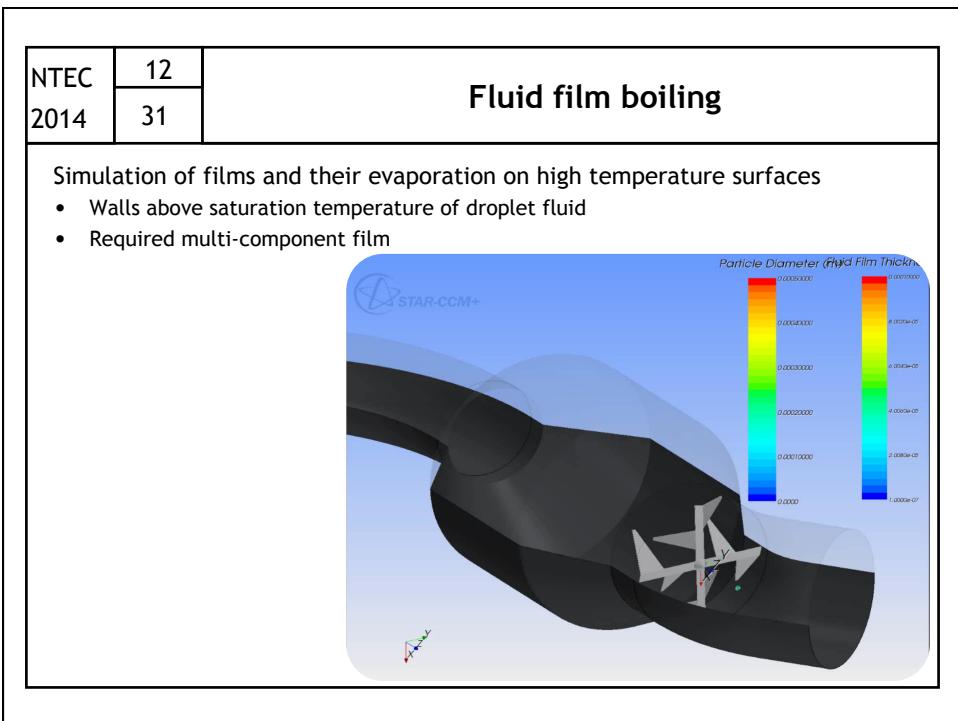
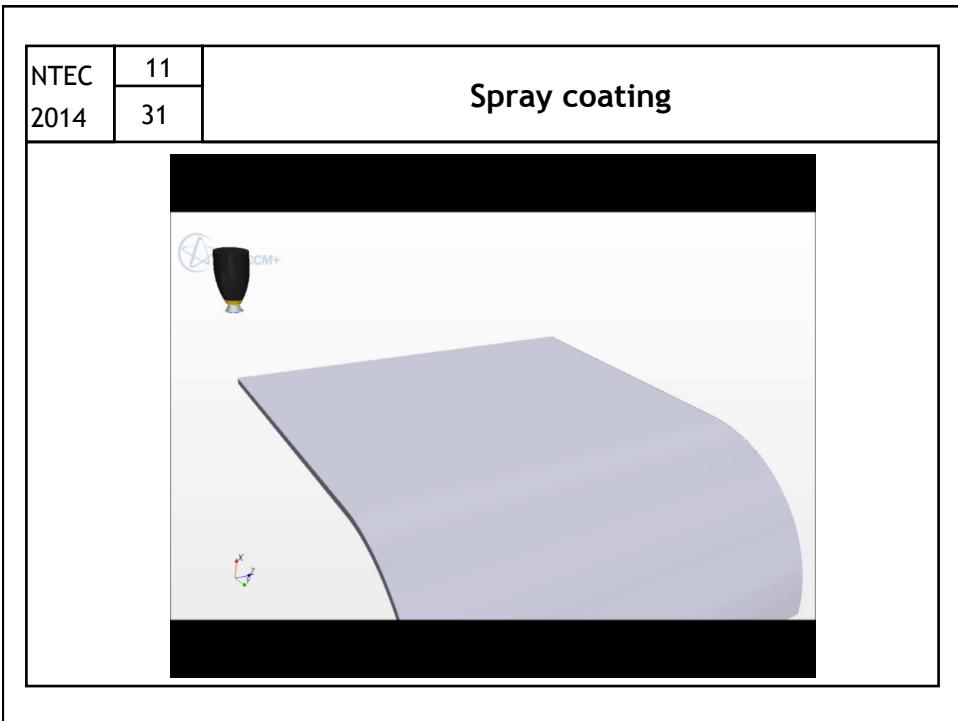
- Equation of motion for individual particle:

$$m_d \frac{du_d}{dt} = F \quad u_d = \frac{dx_d}{dt}$$

- F = force acting on particle







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DEM (Discrete Element Method)

- Linear momentum of particle:

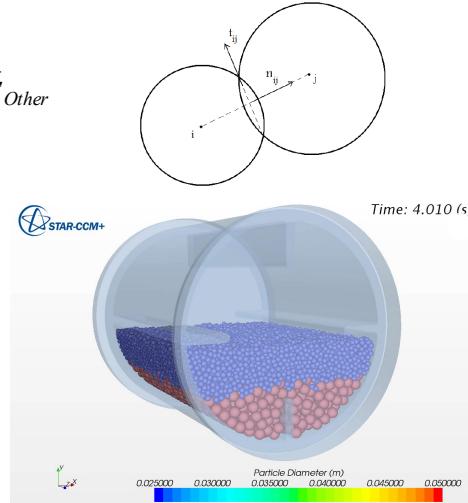
$$m_i \frac{d\vec{v}_i}{dt} = \vec{F}_{Drag} + \vec{F}_{Contact} + \vec{F}_{Other}$$

- Angular momentum:

$$I_i \frac{d\vec{\omega}_i}{dt} = \sum_{j=1}^k [\vec{\tau}_{ij} + \vec{M}_{ij}]$$

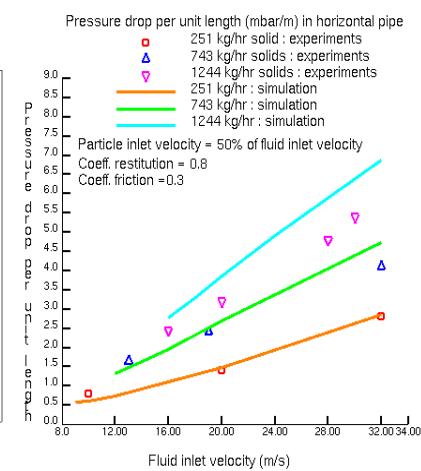
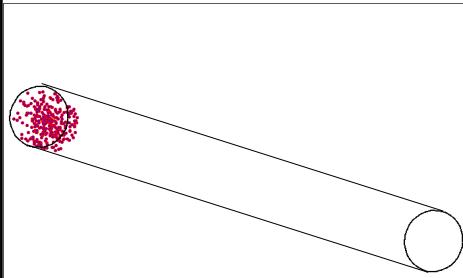
$$\vec{M}_{ij} = -\mu_{roll} |\vec{F}_{Contact}| \vec{\omega}_i$$

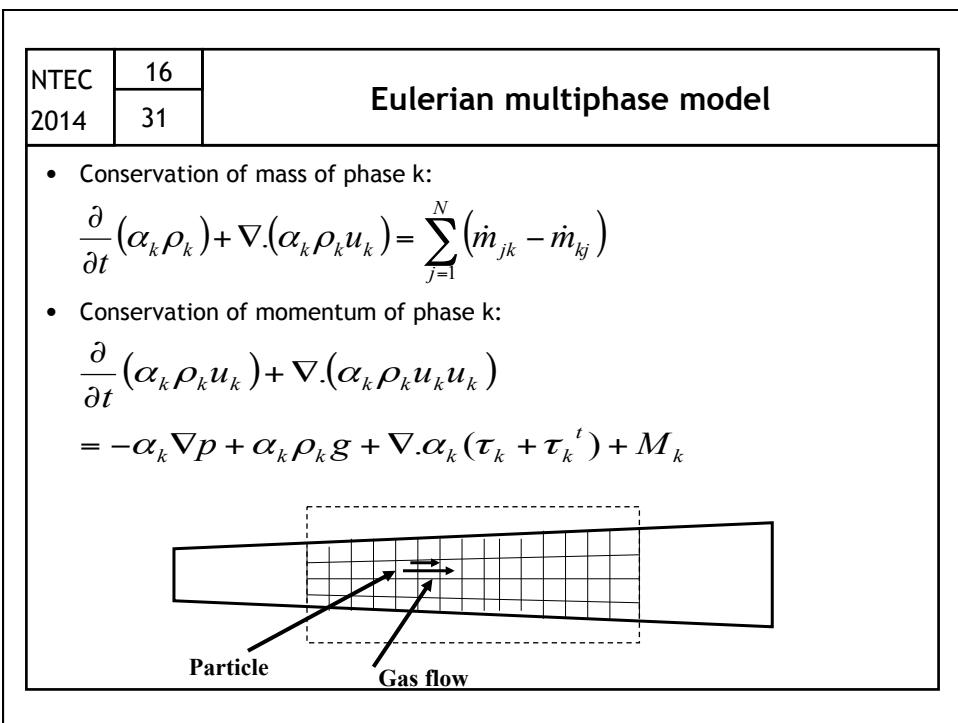
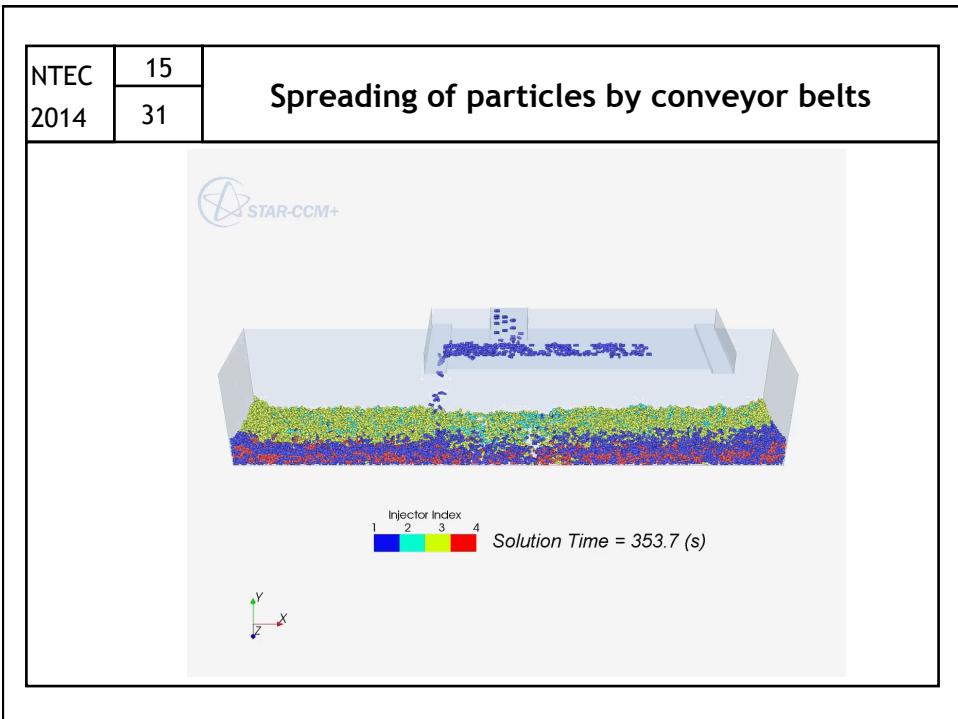
- \vec{M}_{ij} = rolling torque
- μ_{roll} = rolling friction coefficient.



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Pneumatic conveying of particles in pipe

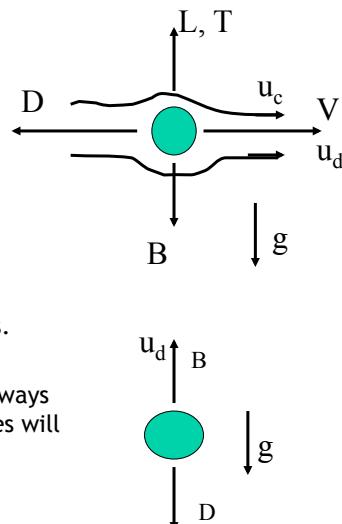




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Forces on a particle

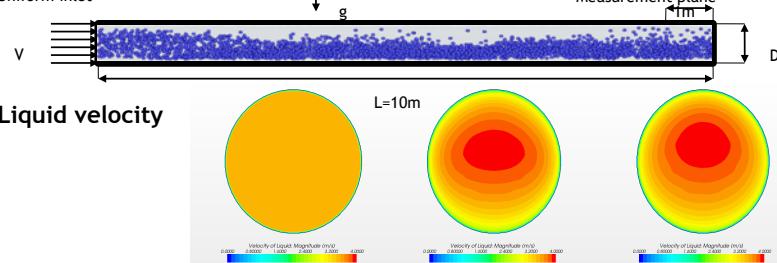
- Forces acting on a particles:
 - Buoyancy, B .
 - Drag, D .
 - Lift, L .
 - Virtual mass, V .
 - Turbulent dispersion, T .
 - Basset force.
 - And others.
- Buoyancy and drag are the dominant ones.
- Basset force is complicated and almost always ignored. Lift, virtual mass and other forces will be considered later.



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Slurry flow in horizontal pipe

Uniform inlet

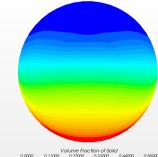
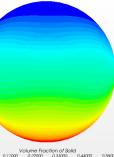


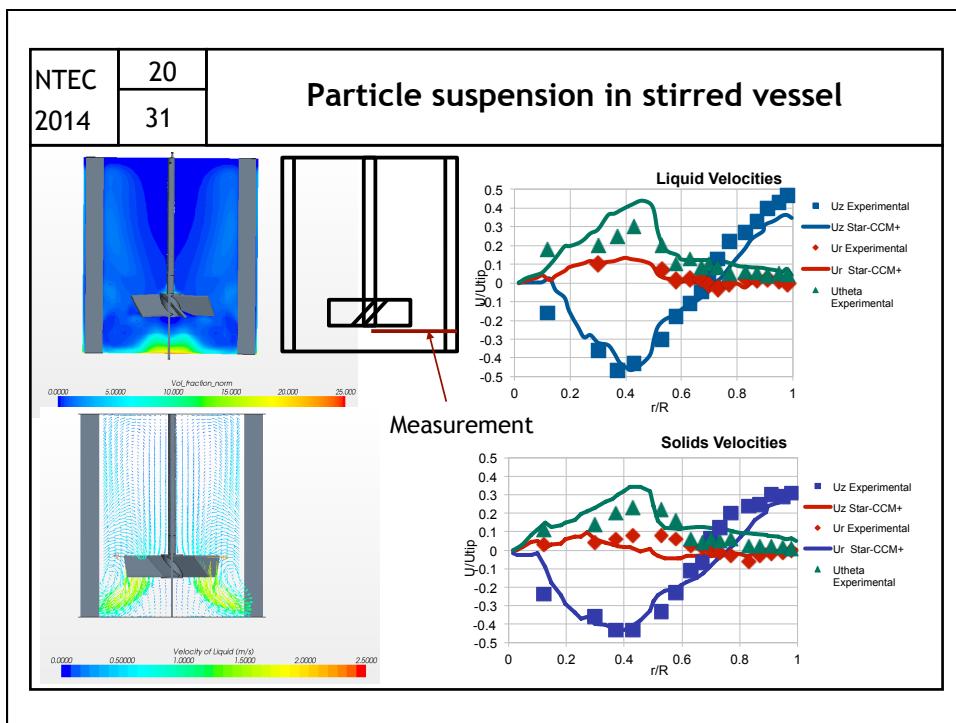
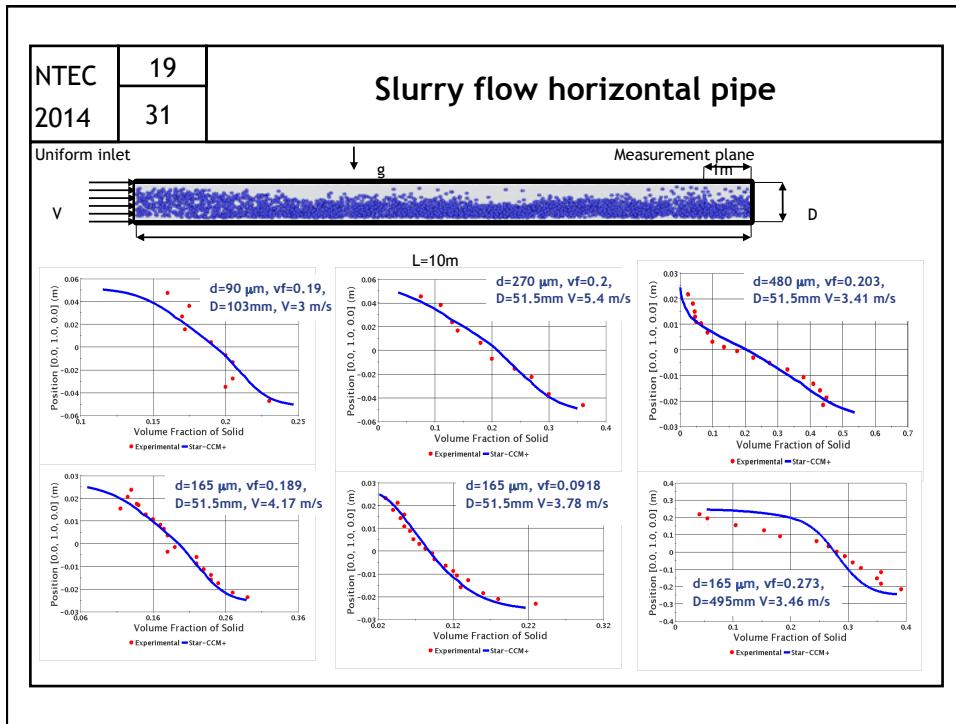
Particle volume fraction

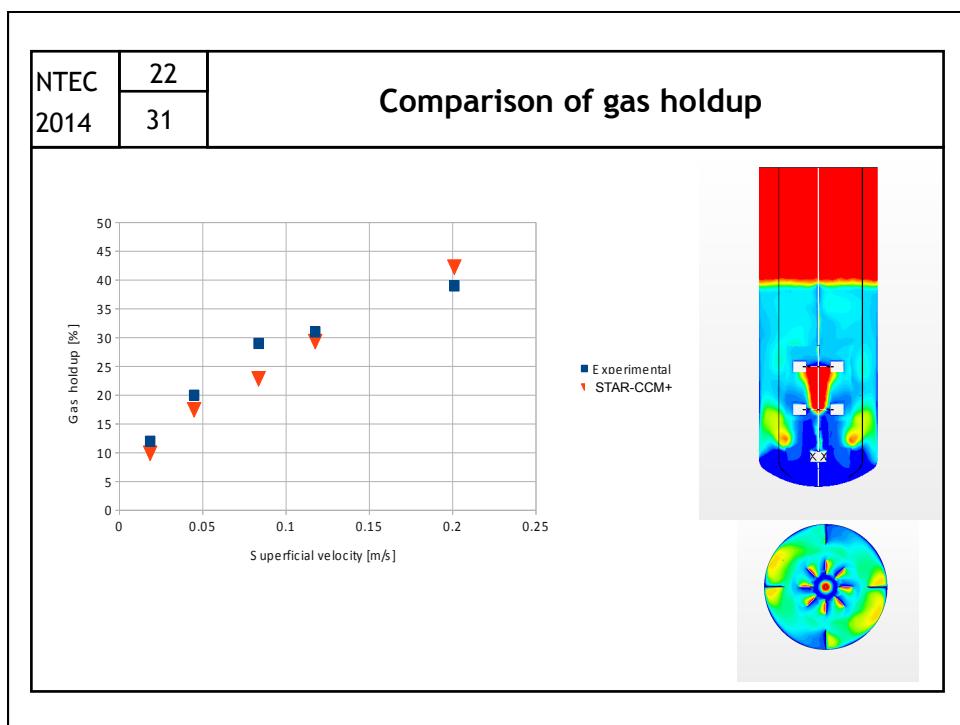
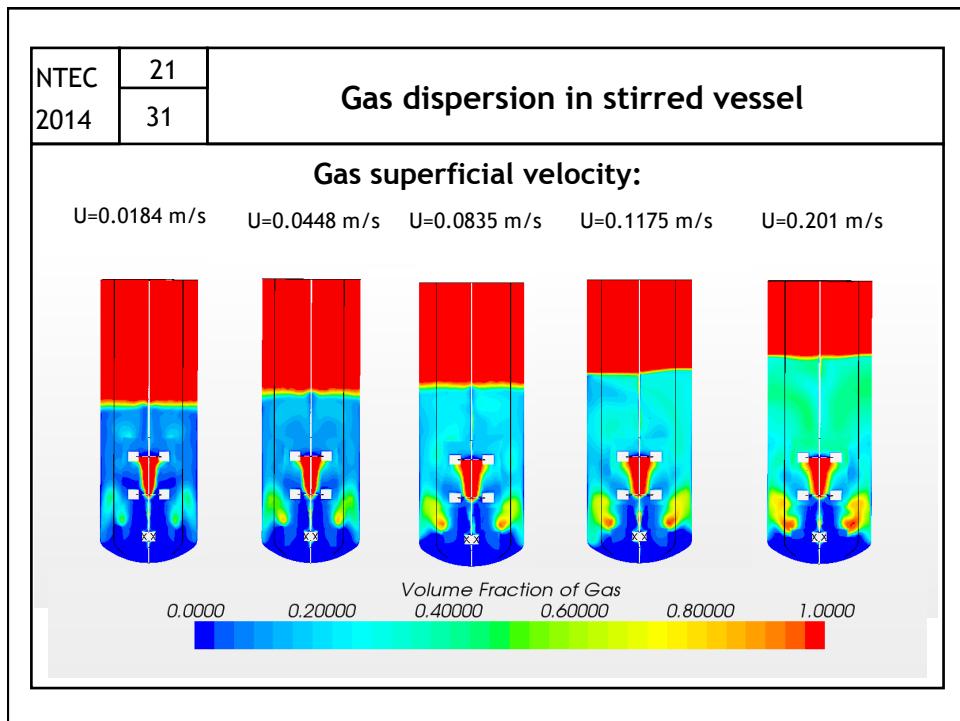
Inlet

Middle

Outlet







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Adaptive MUSIG Model

An Eulerian population balance method for poly-disperse multiphase flows.

$$\frac{\partial \alpha_i \rho_i}{\partial t} + \nabla \cdot (\alpha_i \rho_i \mathbf{u}_i) = \sum_{i \neq j} (m_{ij} - m_{ji}),$$

$$\frac{\partial \alpha_i \rho_i \mathbf{u}_i}{\partial t} + \nabla \cdot (\alpha_i \rho_i \mathbf{u}_i \mathbf{u}_i) = -\alpha_i \nabla P + \sum_{i \neq j} (m_{ij} \mathbf{u}_j - m_{ji} \mathbf{u}_i) + \mathbf{F}_i.$$

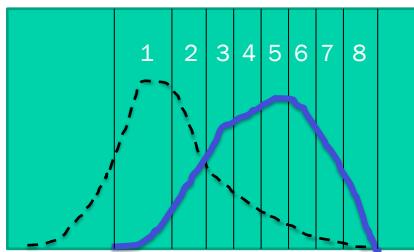
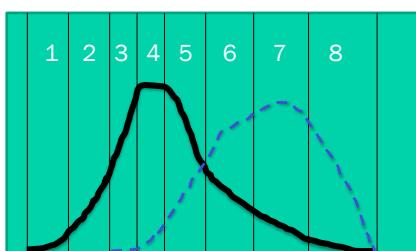
$$\frac{\partial n_i}{\partial t} + \nabla \cdot (n_i \mathbf{u}_i) = S_i,$$

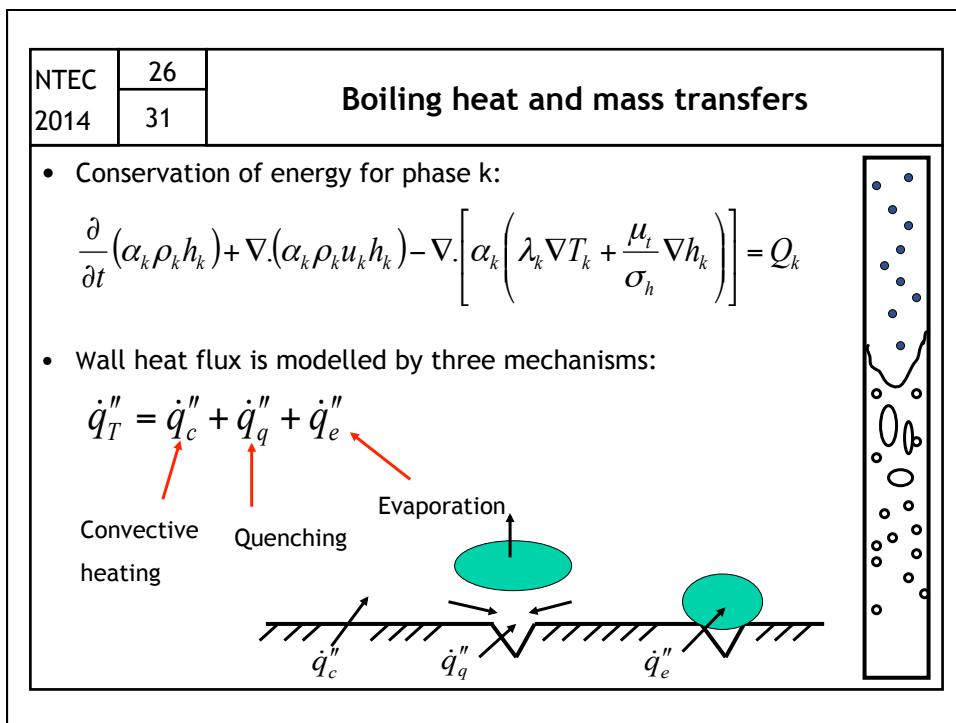
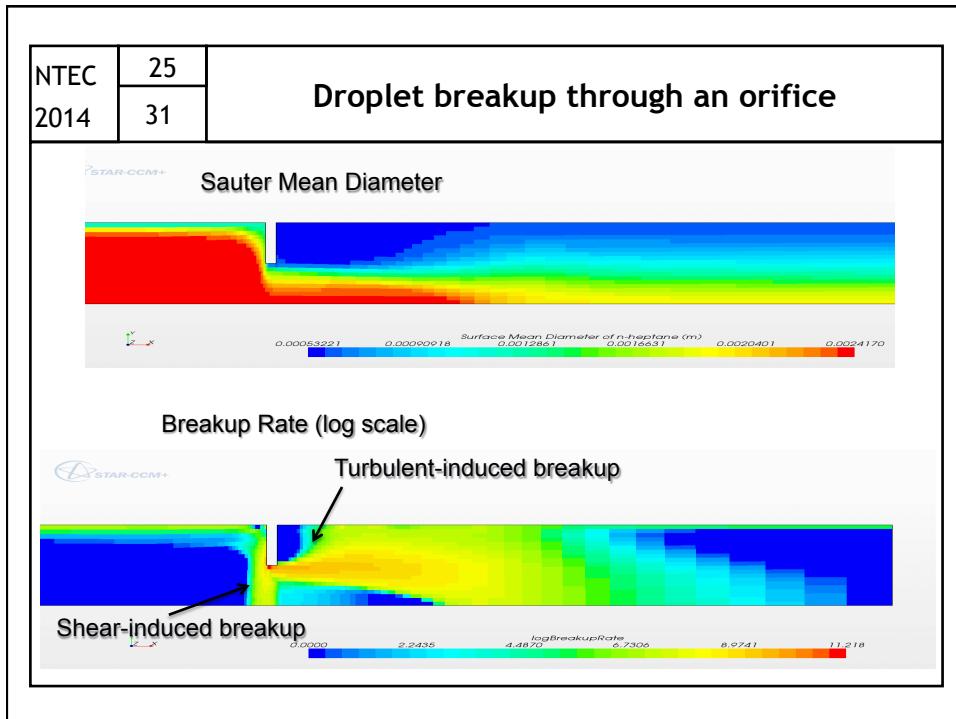
$$d_i = \sqrt[3]{(6\alpha_i)/(\pi n_i)}.$$

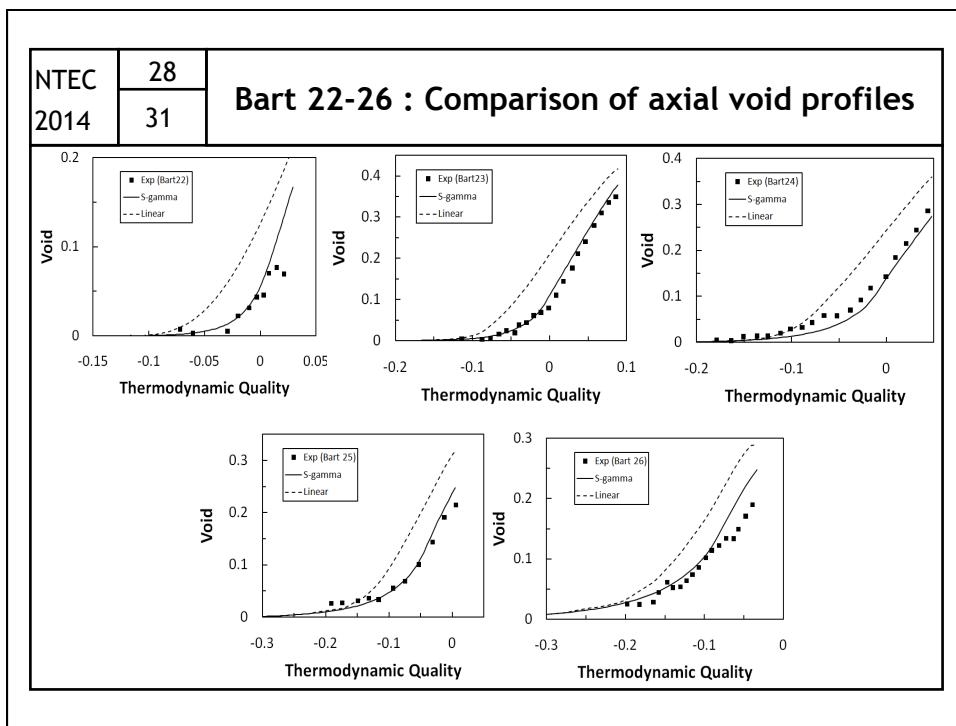
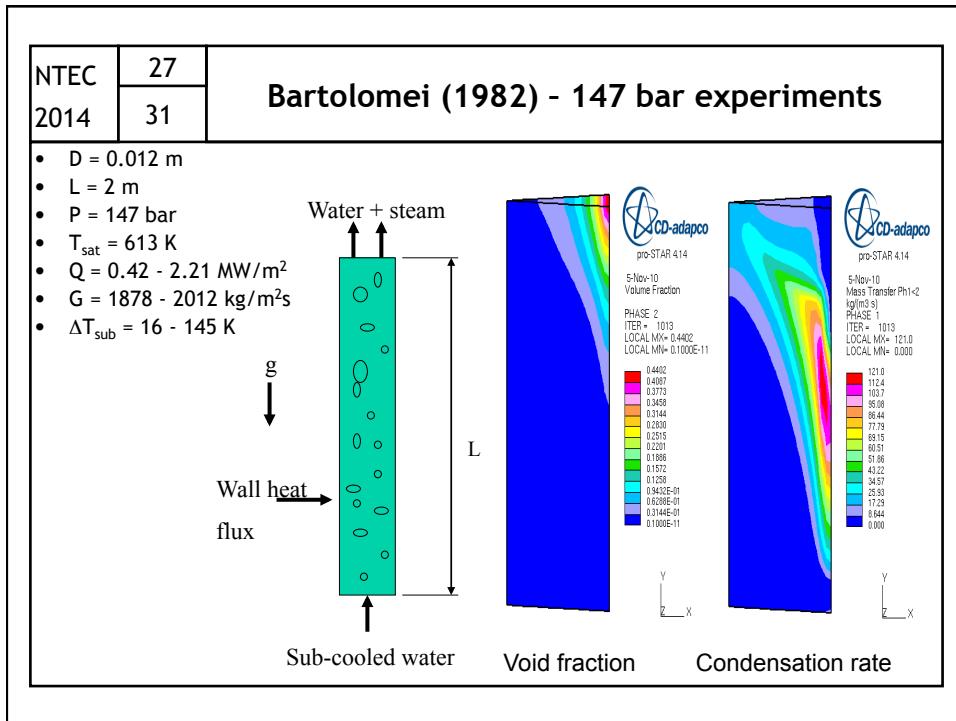
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Adaptive MUSIG Model

Mass and number density are redistributed between neighbour groups so that each group has the same mass but new diameters.







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Multi-component multiphase model

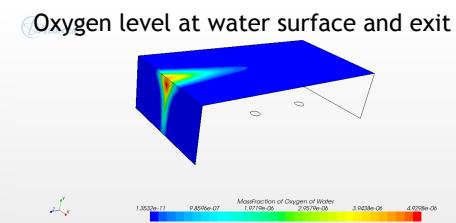
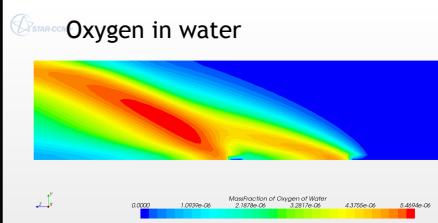
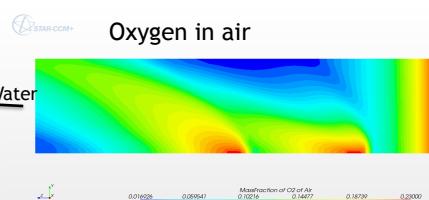
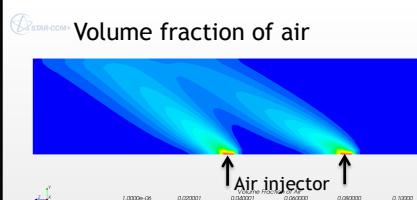
- General species transport equation for phase k is:

$$\frac{\partial}{\partial t}(\alpha_k \rho_k Y_k) + \nabla \cdot (\alpha_k \rho_k u_k Y_k) - \nabla \cdot \left[\alpha_k \left(D_k + \frac{\mu_t}{\sigma_Y} \right) \nabla Y_k \right] = S_k$$

Y = mass fraction of species or other scalar quantity,
 D = diffusion coefficient,
 σ = Schmidt number,
 S = sources.

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Oxygen transfer in aeration tank



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Summary

- VOF
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 - Population balance
 - Boiling heat and mass transfers
 - Interphase mass transfer